

<b>Advanced Control Methods for Adaptive Mechanical Systems</b>					
<b>Module-No./Abbreviation</b>	<b>Credits</b>	<b>Workload</b>	<b>Term</b>	<b>Frequency</b>	<b>Duration</b>
CE-WP13/ ACMAMS	6 CP	180 h	3 <sup>rd</sup> Sem.	Winter term	1 Semester
<b>Courses</b> Advanced Control Theory, Structural Control			<b>Contact hours</b> 4 SWS (60 h)	<b>Self-Study</b> 120 h	<b>Group Size:</b> No Restrictions
<b>Prerequisites</b> Adaptronics (CE-WP03), fundamentals of control theory and structural control.					
<b>Learning goals / Competences</b> Extended knowledge in adaptive mechanical systems, advanced control methods and their application for the active control of structures. After successfully completing the module, the students <ul style="list-style-type: none"> <li>• have advanced knowledge in control systems design,</li> <li>• are able to design full order observer of the states in a state space model,</li> <li>• have basic knowledge in observation using Kalman filter,</li> <li>• have basic knowledge in the system identification of state-space models,</li> <li>• have knowledge in experimental modal analysis,</li> <li>• are able to independently design a velocity feedback vibration suppression for basic mechanical structures.</li> </ul>					
<b>Content</b> Advanced methods for the control of adaptive mechanical systems are introduced in the course. This involves the recapitulation of the fundamentals of active structural control and an extension to advanced control. Observer design is introduced as a tool for the estimation of system states. In addition to numerical modelling using the finite element approach, system identification is explained as an experimental approach. Theoretical backgrounds of the experimental structural modal analysis are introduced along with the terms and definitions used in signal processing. Experimental modal analysis is explained using the Fast Fourier Transform. Advanced closed loop control methods involving optimal discrete-time control, introduction of additional dynamic approaches for the compensation of periodic excitations and basic adaptive control algorithms are explained and pragmatically applied for solving problems of vibration suppression in civil and mechanical engineering.					
<b>Teaching methods / Language</b> Lecture (2h / week), exercises and practical work (2h / week) / English					
<b>Mode of assessment</b> Written examination (120 min, 100%) / Seminar paper					
<b>Requirement for the award of credit points</b> Passed seminar paper and passed final module examination					
<b>Module applicability</b> MSc. Computational Engineering					
<b>Weight of the mark for the final score</b> 6 %					
<b>Module coordinator and lecturer(s)</b> Prof. Dr.-Ing. T. Nestorović, Assistants					
<b>Further information</b>					